| | Hits | Search Text | |
|----|------|--|--|
| 1 | 3071 | automat\$4 and (arm\$2 with gripper) | |
| 2 | 315 | automat\$4 with (arm\$2 with gripper) | |
| 3 | 203 | (automat\$4 with (arm\$2 with gripper)) and rotat\$5 | |
| 4 | 976 | automat\$4 with (arm\$2 with grip\$4) | |
| 5 | 233 | (automat\$4 with (arm\$2 with grip\$4)) and (grip\$4 near4 rotat\$5) | |
| 6 | 216 | (automat\$4 and (arm\$2 with gripper) and telescop\$4) and rotat\$4 | |
| 7 | 4469 | (422/63-67,300-304).CCLS. | |
| 8 | 1305 | ((422/63-67,300-304) CCLS.) and arm\$4 | |
| 9 | 289 | (((422/63-67,300-304) CCLS.) and arm\$4) and grip\$5 | |
| 10 | 247 | ((((422/63-67,300-304).CCLS.) and arm\$4) and grip\$5) and rotat\$5 | |
| 11 | 9 | ((((((422/63-67,300-304).CCLS.) and arm\$4) and grip\$5) and rotat\$5) and telescop\$4 | |
| 12 | 12 | (automat\$4 or robot\$2) with (arm\$2 with gripper) with telescop\$3 | |
| 13 | 120 | (automat\$4 or robot\$2) with ((shaft\$2 or rail\$2) near3 telescop\$3) | |
| 14 | 13 | ((automat\$4 or robot\$2) with ((shaft\$2 or rail\$2) near3 telescop\$3)) with arm\$2 | |
| 15 | 45 | ((automat\$4 or robot\$2) with ((shaft\$2 or rail\$2) near3 / telescop\$3)) and arm\$2 | |

| | - | Hits | Search Text | - |
|---|----|------|--|-----|
| | 16 | 1498 | (automat\$4 or robot\$2) with (arm\$2 with gripper) | |
| | 17 | 93 | ((automat\$4 or robot\$2) with (arm\$2 with gripper)) and (drive near2 belt\$2) | |
| | 18 | 4726 | (901/1-9,14-29).CCLS. | |
| | 19 | 543 | ((901/1-9,14-29).CCLS.) and gripper\$3 | |
| · | 20 | 143 | (((901/1-9,14-29).CCLS.) and gripper\$3) and belt\$2 | Y . |
| | 21 | 2023 | two near2 grippers | |
| | 22 | 49 | (two near2 grippers) near4 drive\$2 | |
| | 23 | 104 | (robot\$4 or automat\$4) and (telescop\$3 near3 height near3 adjust\$5) | |
| | 24 | 61 | ((robot\$4 or automat\$4) and (telescop\$3 near3 height near3 adjust\$5)) and arm\$2 | |
| | 25 | 117 | (robot\$4 or automat\$4) and (telescop\$3 near3 height) and arm\$2 | |
| | 26 | 441 | (automat\$4 or robot\$2) with ((shaft\$2 or rail\$2 or arm\$2 or height) near3 telescop\$3) | |
| | 27 | 95 | ((automat\$4 or robot\$2) with ((shaft\$2 or rail\$2 or arm\$2 or height) near3 telescop\$3)) and height | |
| | 28 | 2 | ("5215377").PN | |
| | 29 | 9 | grippers near4 independent near3 drive\$3 | |
| | 30 | 1098 | grippers near4 drive\$3 | |
| | | | | |
| | | | | |

| | Hits | Search Text |
|----|------|---|
| 31 | 75 | (grippers near4 drive\$3) with arm\$2 |
| 32 | 241 | ((two or pair) near2 grippers) with arm |
| 33 | 18 | (((two or pair) near2 grippers) with arm) with (belt or drive\$2) |
| 34 | 2 | ("6652015").PN. |
| 35 | 289 | ((plural\$4 or two or couple or pair) near2 grippers) with arm |
| 36 | 6 | (("6,080,363") or ("5948159") or ("5,417,123")) PN. |
| 37 | 15 | "2196428" |
| 38 | 3 | "GB 2196428" |
| 39 | 2 | ("4738824").PN. |
| 40 | 2 | ("5,895,628").PN. |